## Problem 1

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## July 8, 2014

Problem

Let  $\theta, \beta$  be  $3 \times 3$  skew-symmetric matrices and  $\sigma$  be a  $3 \times 3$  matrix. Find symmetric S, T such that:

$$(S-\theta)(T-\beta) = \sigma$$

Solution

Assuming nonsingularity whenever necessary From  $(S - \theta)(T - \beta) = \sigma$  we have  $S = \theta + \sigma(T - \beta)^{-1}$ S is hermitian if and only if

$$S = \theta + \sigma (T - \beta)^{-1} = \theta^{\dagger} + ((T - \beta)^{-1})^{\dagger} \sigma^{\dagger}$$

or equivalently:

$$2\theta = (T+\beta)^{-1}\sigma^{\dagger} - \sigma(T-\beta)^{-1}$$
$$2(T+\beta)\theta(T-\beta) = \sigma^{\dagger}(T-\beta) - (T+\beta)\sigma$$
$$2T\theta T + (2\beta\theta - \sigma^{\dagger})T + T(\sigma - 2\theta\beta) - 2\beta\theta\beta + \sigma^{\dagger}\beta + \beta\sigma = 0$$

We denote  $R = 2\theta; A = (2\theta\beta - \sigma); Q = -2\beta\theta\beta + \sigma^{\dagger}\beta + \beta\sigma$ then  $A^{\dagger} = (2\beta\theta - \sigma^{\dagger})$ The equation becomes

$$TRT + A^{\dagger}T - TA + Q = 0$$

with given A and skew-hermitian R, Q.

To find 1 solution we assume that T is diagonal.

To find 1 solution we assume that 1 is diagonal.  
Denote 
$$\mathbf{R} = \begin{pmatrix} 0 & c & b \\ -c & 0 & a \\ -b & -a & 0 \end{pmatrix}, \mathbf{A} = \begin{pmatrix} m_1 & m_2 & m_3 \\ m_4 & m_5 & m_6 \\ m_7 & m_8 & m_9 \end{pmatrix}, \mathbf{Q} = \begin{pmatrix} 0 & q_1 & q_2 \\ -q_1 & 0 & q_3 \\ -q_2 & -q_3 & 0 \end{pmatrix}$$
  
 $\mathbf{T} = \begin{pmatrix} x & 0 & 0 \\ 0 & y & 0 \\ 0 & 0 & z \end{pmatrix}$   
Then we have  $TRT = \begin{pmatrix} 0 & cxy & bxz \\ -cxy & 0 & ayz \end{pmatrix}, A^{\dagger}X = \begin{pmatrix} 0 & m_4y & m_7z \\ m_2x & 0 & m_8z \end{pmatrix}$ 

 $\begin{pmatrix} -bxz & -ayz & 0 \\ m_3x & m_6y & 0 \end{pmatrix}$ Then we have the explicit form of the equation:

$$cxy + m_4y - m_2x = q_1(1)$$
  
 $bxz + m_7z - m_3x = q_2(2)$ 

 $ayz + m_8z - m_6y = q_3(3)$ 

This system of equations is solved by eliminate z (by (2) and (3)) then calculate y from x (by the identity of xy). Then we are left with a quadratic equation of x.

Have x we can solve y, z.

The explicit solution is obtainable but not worth calculated by hand.